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**CENTROAFFINE DIFFERENTIAL GEOMETRY AND
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CENTROAFFINE DIFFERENTIAL GEOMETRY AND ITS RELATIONS TO HORIZONTAL SUBMANIFOLDS

LUC VRANCKEN

ABSTRACT. We relate centroaffine immersions $f : M^n \rightarrow \mathbb{R}^{n+1}$ to horizontal immersions g of M^n into $S_{n+1}^{2n+1}(1)$ or $H_n^{2n+1}(-1)$. We also show that f is an equiaffine sphere, i.e. the centroaffine normal is a constant multiple of the Blaschke normal, if and only if g is minimal.

1. INTRODUCTION

In the present paper, we study centroaffine spheres M^n in \mathbb{R}^{n+1} and ‘horizontal’ immersions M^n in $S_{n+1}^{2n+1}(1)$ and $H_n^{2n+1}(-1)$. The basic existence and uniqueness theorems for those submanifolds together with the necessary preliminaries are derived in Sections 2 and 3. As it turns out, both are essentially determined by a symmetric tensor field on M^n satisfying certain properties. In Section 5, under the additional assumption that M^n is simply connected, we use then these existence and uniqueness theorems to relate the two types of submanifolds. This allows us to translate theorems obtained about centroaffine spheres to corresponding theorems about horizontal immersions.

In particular for surfaces M^2 we obtain a relation between negative definite centroaffine spheres with vanishing Tchebychev form (elliptic affine spheres in the terminology of [LSZ]) and minimal horizontal isometric immersions of M^2 in $S_3^5(1)$. Notice that, from the basic formulas derived in Section 3, such immersions always have ellipse of curvature a circle. However, as is shown in [KSV], also arbitrary minimal immersions with ellipse of curvature a circle in $S_3^5(1)$ play a role in affine differential geometry. These can be used to construct 3-dimensional elliptic affine spheres.

2. CENTROAFFINE DIFFERENTIAL GEOMETRY

First, we recall the basic facts about centroaffine hypersurfaces. However, in order to obtain in the definite case always a positive definite metric, we slightly deviate from the standard approach. For more details and proofs see [SSV, Chapter 6]. Let M be a n -dimensional C^∞ -manifold and let $f : M \rightarrow \mathbb{R}^{n+1}$ be a non-degenerate hypersurface immersion whose position vector is nowhere tangent. Then f can be regarded as a transversal field along itself and we call $\xi = -\epsilon f$ the centroaffine normal, where $\epsilon = \pm 1$. Following Nomizu, we call f together with

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this normalization a centroaffine hypersurface. We get the centroaffine structure equations:

$$(2.1) \quad D_X f_*(Y) = f_*(\nabla_X Y) + h(X, Y)\xi,$$

$$(2.2) \quad D_X \xi = -\epsilon f_*(X).$$

Here we choose $\epsilon = 1$ unless the signature of the second fundamental form with respect to $-f$ is less than $\frac{n}{2}$ in which case we choose $\epsilon = -1$. Here D denotes the canonical flat connection of \mathbb{R}^{n+1} , ∇ is a torsionfree connection on M , called the induced centroaffine connection, and h is a non-degenerate symmetric $(0,2)$ -tensor field, called the centroaffine metric. So (M, h) is a semi-Riemannian manifold and the signature of the metric $\text{sign } h$ satisfies $\text{sign } h \leq \frac{n}{2}$. The corresponding integrability conditions (equations of Gauss (2.3) and Codazzi (2.4)) are

$$(2.3) \quad R(X, Y)Z = h(Y, Z)X - h(X, Z)Y,$$

$$(2.4) \quad (\nabla h)(X, Y, Z) = (\nabla h)(Y, X, Z),$$

where $(\nabla h)(X, Y, Z) = Xh(Y, Z) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z)$. If we define

$$C(X, Y, Z) = (\nabla h)(X, Y, Z),$$

we get a totally symmetric $(0,3)$ -tensor field, called the cubic form.

Denote by $\hat{\nabla}$ the Levi-Civita connection of h , by \hat{R} , \widehat{Ric} and $\hat{\kappa}$ the curvature tensor, the Ricci tensor and the normalized scalar curvature of $\hat{\nabla}$, respectively. The difference tensor K , which is defined by

$$(2.5) \quad K_X Y = K(X, Y) = \nabla_X Y - \hat{\nabla}_X Y,$$

is a symmetric tensor field related to the cubic form by $C(X, Y, Z) = -2h(K_X Y, Z)$. Hence for every X , K_X is selfadjoint with respect to h . Furthermore, we define the Tchebychev form T , the Tchebychev vector field T^\sharp and the Pick invariant J by

$$(2.6) \quad nT(X) = \text{trace } K_X,$$

$$(2.7) \quad h(T^\sharp, X) = T(X),$$

$$(2.8) \quad 4n(n-1)J = 4h(K, K) = h(C, C).$$

We call M an equiaffine sphere if and only if the Tchebychev form vanishes identically. It is well known that in that case, the centroaffine normal is a constant multiple of the Blaschke equiaffine normal. It is also well known that

$$(2.9) \quad h(K_X Y, Z) = h(Y, K_X Z),$$

$$(2.10)$$

$$\hat{R}(X, Y)Z = K_Y K_X Z - K_X K_Y Z + \epsilon(h(Y, Z)X - h(X, Z)Y),$$

$$(2.11)$$

$$(\hat{\nabla} K)(X, Y, Z) = (\hat{\nabla} K)(Y, X, Z),$$

$$(2.12)$$

$$\hat{\kappa} = J + \epsilon - \frac{n}{n-1}h(T^\sharp, T^\sharp),$$

where ϵ is as defined before. Then, we have the following existence theorem:

Theorem 2.1. *Let (M, h) be an n -dimensional simply connected semi-Riemannian manifold with $\text{sign } h \leq \frac{n}{2}$. Let $\epsilon = \pm 1$ and let K be a symmetric tensor field on M satisfying (2.9), (2.10), (2.11). Then there exist a centroaffine immersion $f : M^n \rightarrow \mathbb{R}^{n+1}$ with $\xi = -\epsilon f$ as affine normal, h as affine metric and $\nabla = K + \hat{\nabla}$, where $\hat{\nabla}$ is the Levi Civita connection of the metric h , as induced affine connection. Moreover, the immersion f is unique up to centroaffine transformations.*

Proof. In order to obtain the existence part, we define a connection ∇ on M by

$$\nabla_X Y = K(X, Y) + \hat{\nabla}_X Y,$$

where $\hat{\nabla}$ is the Levi Civita connection of the semi-Riemannian metric h . Then, we have that

$$\begin{aligned} (\nabla h)(X, Y, Z) &= Xh(Y, Z) - h(\nabla_X Y, Z) - h(Y, \nabla_X Z) \\ &= h(\hat{\nabla}_X Y, Z) + h(Y, \hat{\nabla}_X Z) - h(K(X, Y), Z) \\ &\quad - h(\hat{\nabla}_X Y, Z) - h(Y, K(X, Z)) - h(Y, \hat{\nabla}_X Z) \\ &= -2h(K(X, Y), Z). \end{aligned}$$

Hence by (2.9) we deduce that $(\nabla h)(X, Y, Z)$ is totally symmetric. Next, we have that

$$\begin{aligned} R(X, Y)Z &= \nabla_X \nabla_Y Z - \nabla_Y \nabla_X Z - \nabla_{[X, Y]} Z, \\ &= K(X, \nabla_Y Z) + \hat{\nabla}_X \nabla_Y Z - K(Y, \nabla_X Z) \\ &\quad - \hat{\nabla}_Y \nabla_X Z - K([X, Y], Z) - \hat{\nabla}_{[X, Y]} Z \\ &= K(X, K(Y, Z)) - K(Y, K(X, Z)) + \hat{R}(X, Y)Z \\ &\quad + (\hat{\nabla} K)(X, Y, Z) - (\hat{\nabla} K)(Y, X, Z) \\ &= \epsilon(h(Y, Z)X - h(X, Z)Y). \end{aligned}$$

Finally, we define the affine shape operator by $S = \epsilon I$. Applying now the general existence theorem of [DNV], we obtain that there exists an affine immersion $f : M^n \rightarrow \mathbb{R}^{n+1}$ and a transversal vector field ξ such that we can write

$$\begin{aligned} D_X f_* Y &= f_* \nabla_X Y + h(X, Y)\xi, \\ D_X \xi &= -f_* S X = -\epsilon X. \end{aligned}$$

Since $D_X(f + \epsilon \xi) = 0$, we obtain that if necessary by applying a translation, we may assume that f is centroaffine.

Next, we show the uniqueness part. Let $f_1, f_2 : M^n \rightarrow \mathbb{R}^{n+1}$ be two immersions satisfying the assumptions of the theorem. Applying the uniqueness theorem [D], see also [DNV], we have that f_1 and f_2 are related by an affine transformation. It then follows from (2.1) and the definition of ξ that the translation component is zero. Hence f_1 and f_2 are related by a centroaffine transformation. \square

3. HORIZONTAL SUBMANIFOLDS

We consider \mathbb{R}^{2n+2} and we take $p = (x_1, y_1, x_2, y_2, \dots, x_n, y_n)$ a point of \mathbb{R}^{2n+2} . We define a product structure P on \mathbb{R}^{2n+2} , by

$$P(x_1, y_1, \dots, x_{n+1}, y_{n+1}) = (y_1, x_1, \dots, y_{n+1}, x_{n+1}),$$

and we introduce a metric $\langle \cdot, \cdot \rangle$ on \mathbb{R}^{2n+2} by

$$(3.1) \quad \langle (v_1, w_1, \dots, v_{n+1}, w_{n+1}), (\tilde{v}_1, \tilde{w}_1, \dots, \tilde{v}_{n+1}, \tilde{w}_{n+1}) \rangle = \sum_{i=1}^{n+1} v_i \tilde{v}_i - \sum_{i=1}^{n+1} w_i \tilde{w}_i.$$

Hence $\text{sign} \langle \cdot, \cdot \rangle = n + 1$. It immediately follows from (3.1) that for vectors x and y we have that

$$(3.2) \quad \langle Px, Py \rangle = -\langle x, y \rangle.$$

In particular this implies that

$$\langle x, Px \rangle = -\langle Px, P^2x \rangle = -\langle Px, x \rangle.$$

Hence

$$(3.3) \quad \langle x, Px \rangle = 0.$$

We also deduce that $(D_V P)W = 0$, where D is the standard connection on \mathbb{R}^{2n+2} . Let $S_{n+1}^{2n+1}(1)$ and $H_n^{2n+1}(-1)$ be the spaces respectively defined by

$$S_{n+1}^{2n+1}(1) = \{p \in \mathbb{R}^{n+2} \mid \langle p, p \rangle = 1\}$$

and

$$H_n^{2n+1}(-1) = \{p \in \mathbb{R}^{n+2} \mid \langle p, p \rangle = -1\}.$$

It immediately follows that $S_{n+1}^{2n+1}(1)$ is an umbilical hypersurface of \mathbb{R}^{2n+2} , with $-p$ as normal and that the signature of the induced metric is $n + 1$. Similarly, it follows that also $H_n^{2n+1}(-1)$ is an umbilical hypersurface with normal p and with signature of the induced metric equal to n . We denote by $\tilde{M}(1) = S_{n+1}^{2n+1}(1)$ and by $\tilde{M}(-1) = H_n^{2n+1}(-1)$. We now say that an immersion $f : M^n \rightarrow \tilde{M}(\epsilon)$, where $\epsilon = \pm 1$, is horizontal if and only if Pf is orthogonal to f_*T_pM . Notice that it follows from (3.3) that Pf is always a tangent vector field to $\tilde{M}(\epsilon)$. Decomposing the connection D into a tangent component, a normal component which is tangent to $\tilde{M}(\epsilon)$ and a component in the direction of the position vector, we see that

$$\begin{aligned} D_X f_* Y &= f_*(\nabla_X Y) + \alpha(X, Y) - \langle X, Y \rangle \epsilon f, \\ D_X \eta &= -f_* A_\eta X + \nabla_X^\perp \eta, \end{aligned}$$

where X, Y are tangent vector fields and η is a normal vector field to M tangent to $\tilde{M}(\epsilon)$. The symmetric bilinear form α is the second fundamental form of the

immersion f in $\tilde{M}(\epsilon)$ and ∇^\perp is the normal connection of the immersion f in $\tilde{M}(\epsilon)$. Since for a horizontal immersion, we have that $\langle Pf, X \rangle = 0$, for any tangent vector field X , we deduce that

$$0 = \langle Pf_*(Y), X \rangle + \langle Pf, \alpha(X, Y) \rangle.$$

From (3.2) it follows that the first term is skewsymmetric in X and Y , whereas the second term is symmetric. Hence we obtain that

$$(3.4) \quad \begin{aligned} \langle Pf_*(X), Y \rangle &= 0, \\ \langle Pf, \alpha(X, Y) \rangle &= 0. \end{aligned}$$

Hence $A_{Pf} = 0$ and P maps the tangent space into the normal space of M in $\tilde{M}(\epsilon)$. Therefore the normal space to M in $\tilde{M}(\epsilon)$ is spanned by Pf and Pf_*TM . Deriving the first equation of (3.4), and identifying M with its image in \mathbb{R}_{n+1}^{2n+2} we deduce that

$$(3.5) \quad 0 = \langle PX, \alpha(Y, Z) \rangle - \langle A_{PX}Z, Y \rangle.$$

Since P is parallel with respect to D , we deduce that

$$\begin{aligned} 0 &= (D_X P)f \\ &= D_X Pf - PD_X f \\ &= \nabla_X^\perp Pf - PX. \end{aligned}$$

Hence

$$(3.6) \quad \nabla_X^\perp Pf = PX.$$

Similarly, we get that

$$\begin{aligned} 0 &= (D_X P)Y = D_X PY - PD_X Y, \\ &= \nabla_X^\perp PY - A_{PY}X - P\nabla_X Y - P\alpha(X, Y) + \epsilon \langle X, Y \rangle Pf. \end{aligned}$$

Hence,

$$(3.7) \quad \begin{aligned} \nabla_X^\perp PY &= P\nabla_X Y - \epsilon \langle X, Y \rangle Pf, \\ A_{PY}X &= -P\alpha(X, Y). \end{aligned}$$

Finally, we recall that the equations of Gauss, Codazzi and Ricci for submanifolds of a semi-Riemannian space form state that

$$(3.8) \quad \begin{aligned} R(X, Y)Z &= \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y) + A_{\alpha(Y, Z)}X - A_{\alpha(X, Z)}Y, \\ (\nabla\alpha)(X, Y, Z) &= (\nabla\alpha)(Y, X, Z), \\ \langle R^\perp(X, Y)\eta_1, \eta_2 \rangle &= \langle [A_{\eta_1}, A_{\eta_2}]X, Y \rangle. \end{aligned}$$

We introduce a symmetric bilinear form β on M by

$$\beta(X, Y) = -P\alpha(X, Y) = A_{PY}X = A_{PX}Y.$$

We also write $\beta_X Y = \beta_Y X = \beta(X, Y)$. From (3.5) it follows that

$$(3.9) \quad \langle \beta(X, Y), Z \rangle \text{ is symmetric in } X, Y \text{ and } Z.$$

It now follows from (3.6) and (3.7) that we can rewrite

$$\begin{aligned} R(X, Y)Z &= \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y) - A_{PA_{PY}Z}X + A_{PA_{PX}Z}Y \\ &= \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y - A_{PX}A_{PY}Z + A_{PY}A_{PX}Z) \\ &= \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y) - \beta(X, \beta(Y, Z)) + \beta(Y, \beta(X, Z)) \\ (3.10) \quad &= \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y) - [\beta_X, \beta_Y]Z, \end{aligned}$$

From (3.6), (3.7) and the Codazzi equation it follows that

$$\begin{aligned} (\nabla\beta)(X, Y, Z) &= \nabla_X\beta(Y, Z) - \beta(\nabla_X Y, Z) - \beta(X, \nabla_Y Z) \\ &= -\nabla_X P\alpha(Y, Z) + P\alpha(\nabla_X Y, Z) + P\alpha(Y, \nabla_X Z) \\ &= -P\nabla_X^\perp \alpha(Y, Z) + \epsilon\langle X, P\alpha(Y, Z) \rangle f + P\alpha(\nabla_X Y, Z) + P\alpha(Y, \nabla_X Z) \\ (3.11) \quad &= -P(\nabla\alpha)(X, Y, Z) - \epsilon\langle PX, \alpha(Y, Z) \rangle. \end{aligned}$$

Since $\langle PX, \alpha(Y, Z) \rangle = \langle X, \beta(Y, Z) \rangle$ is totally symmetric in X, Y and Z , we deduce that $\nabla\beta$ is totally symmetric if and only if $\nabla\alpha$ is totally symmetric. We now can formulate the basic existence and uniqueness theorems for horizontal submanifolds.

Theorem 3.1. *Let $f_1, f_2: M \rightarrow \tilde{M}(\epsilon)$ be two isometric horizontal immersions. Suppose that $\beta^{f_1} = \beta^{f_2}$. Then there exists an isometry A of $\tilde{M}(\epsilon)$ such that $Af_1 = f_2$.*

Proof. Let $p \in M$. We define an isometry A_p of $\tilde{M}(\epsilon)$ by

$$\begin{aligned} A_p f_1(p) &= f_2(p), \\ A_p f_{1*}(X(p)) &= f_{2*}(X(p)), \\ A_p P f_1(p) &= P f_2(p), \\ A_p P f_{1*}(X(p)) &= P f_{2*}(X(p)). \end{aligned}$$

Now, we show that A is independent of the choice of p . Using the previous equations, it follows that

$$\begin{aligned} (D_X A)f_1 &= D_X(Af_1) - AD_X f_1 \\ &= D_X f_2 - Af_{1*}X = 0, \\ (D_X A)(P f_1) &= D_X(P f_2) - AD_X(P f_1) \\ &= P f_{2*}X - AP f_{1*}X = 0, \\ (D_X A)(f_{1*}(Y)) &= D_X f_{2*}Y - AD_X f_{1*}Y \\ &= f_{2*}(\nabla_X Y) + \alpha^{f_2}(X, Y) - Af_{1*}(\nabla_X Y) - A\alpha^{f_1}(X, Y) \\ &= -P f_{2*}(\beta^{f_2}(X, Y)) + AP f_{1*}(\beta^{f_1}(X, Y)) = 0, \\ (D_X A)(P f_{1*}Y) &= D_X P f_{2*}(Y) - AD_X P f_{1*}Y \\ &= P D_X f_{2*}(Y) - AP D_X f_{1*}Y \\ &= P\alpha^{f_2}(X, Y) - AP\alpha^{f_1}(X, Y) \\ &= -f_{2*}\beta^{f_2}(X, Y) + Af_{1*}\beta^{f_1}(X, Y) = 0. \end{aligned}$$

This completes the proof of the theorem. \square

Theorem 3.2. *Let $(M, \langle \cdot, \cdot \rangle)$ be a simply connected semi-Riemannian manifold. Let β be a symmetric bilinear vector valued 2 form on M such that*

- (1) $\langle \beta(X, Y), Z \rangle$ is totally symmetric,
- (2) $\nabla \beta$ is totally symmetric,
- (3) $R(X, Y)Z = \epsilon(\langle Y, Z \rangle X - \langle X, Z \rangle Y) - [\beta_X, \beta_Y]Z$.

Then there exists a horizontal isometric immersion $f : M \rightarrow \tilde{M}(\epsilon)$ with second fundamental form α such that $\beta(X, Y) = -P\alpha(X, Y)$.

Proof. We define a bundle NM over M by $NM = TM \oplus \mathbb{R} \oplus \mathbb{R}$ and we define a mapping $P : TM \oplus NM \rightarrow TM \oplus NM$ by

$$\begin{aligned} P(X, 0, 0, 0) &= (0, X, 0, 0) \\ P(0, X, 0, 0) &= (X, 0, 0, 0) \\ P(0, 0, 1, 0) &= (0, 0, 0, 1) \\ P(0, 0, 0, 1) &= (0, 0, 1, 0), \end{aligned}$$

a section $f = 0 \oplus 0 \oplus 1$ of NM . We introduce a metric on NM by

$$\begin{aligned} \langle PX, PY \rangle &= -\langle X, Y \rangle & \langle PX, f \rangle &= 0 & \langle X, Pf \rangle &= 0, \\ \langle X, f \rangle &= 0 & \langle PX, Pf \rangle &= 0 & \langle X, PY \rangle &= 0, \\ \langle Pf, Pf \rangle &= -\epsilon & \langle Pf, f \rangle &= 0 & \langle f, f \rangle &= \epsilon. \end{aligned}$$

Next, we define a connection ∇^\perp on NM by

$$\begin{aligned} \nabla_X^\perp PY &= P\nabla_X Y - \epsilon \langle X, Y \rangle Pf, \\ \nabla_X^\perp f &= 0, \\ \nabla_X^\perp Pf &= PX. \end{aligned}$$

Then we define a second fundamental form

$$\gamma : TM \times TM \longrightarrow NM : (X, Y) \mapsto \gamma(X, Y) = -P\beta(X, Y) + \langle X, Y \rangle \epsilon f$$

with corresponding Weingarten operators given by

$$\begin{aligned} A_{PX}Y &= \beta(X, Y), \\ A_{Pf}Y &= 0, \\ A_fY &= -Y, \end{aligned}$$

for X, Y tangent to M .

A straightforward computation then shows that the Gauss, Codazzi and Ricci equations are satisfied and hence by the existence and uniqueness theorem for immersions into real space forms, there exist an isometric immersion $g : M^n \rightarrow \mathbb{R}_{n+1}^{2n+2}$ with $\langle \cdot, \cdot \rangle$ as induced metric and a bundle isomorphism such that we can identify

NM with the normal bundle of g in \mathbb{R}_{n+1}^{2n+2} . Since $D_X(g - f) = 0$, we see that after applying a translation, we may assume that $g = f$. Hence

$$\langle g, g \rangle = \langle f, f \rangle = \epsilon,$$

and $g(M^n) \subset \tilde{M}(\epsilon)$. Since $g = f$ is normal to $\tilde{M}(\epsilon)$, we deduce that the second fundamental form α of M^n in $\tilde{M}(\epsilon)$ is given by $\alpha(X, Y) = -P\beta(X, Y)$.

Finally, in order to show that M^n is horizontal, it is sufficient to show that the mapping P , defined in the beginning of the proof, is parallel along M^n . We have

$$\begin{aligned} (D_X P)Y &= D_X PY - PD_X Y \\ &= \nabla_X^\perp PY - A_{PY} X - P\nabla_X Y - P\gamma(X, Y) \\ &= -\epsilon \langle X, Y \rangle Pf - \beta(X, Y) + \beta(X, Y) + \epsilon \langle X, Y \rangle Pf, \\ (D_X P)PY &= D_X Y - PD_X PY \\ &= P(PD_X Y - D_X PY) \\ &= -P(D_X P)Y = 0, \\ (D_X P)f &= D_X Pf - PD_X f \\ &= PX - PX = 0, \\ (D_X P)Pf &= -P(D_X P)f = 0. \end{aligned} \quad \square$$

4. A CORRESPONDENCE THEOREM

In this section, we relate the two types of submanifolds studied in the previous sections. First, we show:

Theorem 4.1. *Let M be a simply connected manifold. Let $f : M^n \rightarrow \mathbb{R}^{n+1}$ be a centroaffine sphere with difference tensor K and induced metric h . Then there exists a unique isometric horizontal immersion $g : (M^n, h) \rightarrow \tilde{M}(\epsilon)$ with second fundamental form $\alpha(X, Y) = -PK(X, Y)$.*

Proof. The uniqueness part follows immediately from Theorem 3.1. To obtain the existence, we notice that (2.9), (2.10) and (2.11) state that K is a symmetric bilinear form on the semi-Riemannian manifold (M, h) satisfying the conditions of Theorem 3.2. \square

The converse is stated in the next theorem:

Theorem 4.2. *Let M be a simply connected manifold. Let $g : (M^n, \langle \cdot, \cdot \rangle) \rightarrow \tilde{M}(\epsilon)$ be a horizontal isometric immersion with second fundamental form α . Assume that $\text{index} \langle \cdot, \cdot \rangle \leq \frac{n}{2}$. Then there exist a unique $f : M \rightarrow \mathbb{R}^{n+1}$ centroaffine sphere such that the difference tensor K satisfies $K = -P\alpha$.*

Proof. The uniqueness part is clear from Theorem 2.1, whereas the existence part follows by combining (3.9), (3.10) and (3.11) with Theorem 2.1. \square

From the above theorems and (2.6) it is clear that f is an equiaffine sphere if and only if g is minimal. Applying the above theorems now for example to the results of [VLS] and [LSZ, Theorem 2.4.8], we obtain the following corollaries:

Corollary 4.1. *Let $(M, \langle \cdot, \cdot \rangle)$ be a Riemannian manifold and let $g : M^n \rightarrow S_{n+1}^{2n+1}(1)$ be an isometric horizontal minimal immersion. If M^n has constant sectional curvature, then M^n is totally geodesic.*

Corollary 4.2. *Let $(M, \langle \cdot, \cdot \rangle)$ be a complete Riemannian manifold and $g : M^n \rightarrow S_{n+1}^{2n+1}(1)$ a minimal isometric horizontal immersion. Then M^n is totally geodesic.*

Corollary 4.3. *Let $(M, \langle \cdot, \cdot \rangle)$ be a Riemannian manifold and $g : M^n \rightarrow H_n^{2n+1}(-1)$ a minimal isometric horizontal immersion. Assume that M^n has constant sectional curvature. Then either*

- (1) M^n is totally geodesic,
- (2) $g(M^n)$ is congruent to an open part of

$(\sinh u_1, \cosh u_1, \dots, \sinh u_n, \cosh u_n, \sinh -(u_1 + \dots + u_n), \cosh -(u_1 + \dots + u_n)).$

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